# COMPUTING IRREDUCIBLE REPRESENTATIONS OF SUPERSOLVABLE GROUPS 

ULRICH BAUM AND MICHAEL CLAUSEN


#### Abstract

Recently, it has been shown that the ordinary irreducible representations of a supersolvable group $G$ of order $n$ given by a power-commutator presentation can be constructed in time $O\left(n^{2} \log n\right)$. We present an improved algorithm with running time $O(n \log n)$.


## 1. Introduction

In general, computing the ordinary irreducible representations of a given finite group seems to be a hard problem. In their 1990 breakthrough paper [1], Babai and Ronyai have shown that this problem can be solved in time polynomial in the order of the group. Yet their (general-purpose) algorithm does not appear feasible in a practical sense.

However, one can do much better for special classes of finite groups. In this paper, we consider the class of supersolvable groups. Recall that these are finite groups whose chief factors are cyclic of prime order. Recently, Baum [2] has shown that the irreducible representations of supersolvable groups $G$, given by a power-commutator presentation, can be constructed in time $O\left(|G|^{2} \log |G|\right)$. This algorithm has been implemented and has proved quite efficient in practice. Its main tool is the concept of symmetry-adapted representations, which will be briefly discussed in the next section. It has been shown in [2] that the irreducible representations of a supersolvable group adapted to a chief series are always monomial. The proof gives rise to an efficient construction along the chief series of the irreducible representations over any field containing a primitive $e$ th root of unity, where $e$ is the exponent of the group. During the construction, no field arithmetic is needed at all. Only symbolic calculations in the group of $e$ th roots of unity are required. Hence, the symbolic result is valid if interpreted over any field containing a primitive $e$ th root of unity. The structure of this algorithm is basically bottom-up. However, it contains a recursive subroutine, which turned out to be the most expensive part.

In this paper, we present an improved algorithm whose running time has order $|G| \log |G|$. It is based on the same ideas as the old algorithm, but the procedure has been completely reorganized to be purely bottom-up and nonrecursive.

[^0]
## 2. Symmetry-adapted representations

In this section, we recall the concept of symmetry-adapted representations, which will be an important tool in our construction. Let $G$ be a finite group of exponent $e$, and $K$ a field containing a primitive $e$ th root of unity. (According to a theorem by R. Brauer, $K$ is a splitting field for every subgroup of $G$.) Let $\mathscr{T}=\left(G=G_{n}>\cdots>G_{0}=\{1\}\right)$ be a chain of subgroups of $G$. A matrix representation $D$ of $G$ over $K$ is called $\mathscr{T}$-adapted if for all $j, 0 \leq j \leq n$, the following two conditions hold:

- the restriction $D \downarrow G_{j}$ of $D$ to $G_{j}$ is equal to a direct sum of irreducible matrix representations of $G_{j}$;
- equivalent irreducible constituents of $D \downarrow G_{j}$ are equal.

Symmetry-adapted representations have been applied to various mathematical and physical problems, see, e.g., [4]. In particular, the most efficient algorithms for computing discrete Fourier transforms on finite groups are based on this concept [2,3].

It is easy to see that every representation of $G$ is equivalent to a $\mathscr{T}$-adapted representation. In our construction, $\mathscr{T}$ will be a chief series of the supersolvable group $G$; i.e., every $G_{i}$ is normal in $G$ and all indices [ $G_{i}: G_{i-1}$ ] $=: p_{i}$ are prime. In this case, $\mathscr{T}$-adapted representations are almost unique.
Theorem 2.1. Let $\mathscr{T}$ be a chief series of the supersolvable group $G$, and suppose that $D$ and $\Delta$ are two equivalent irreducible and $\mathscr{T}$-adapted $K$-representations of $G$ of degree $d$. Then the intertwining space

$$
\operatorname{Int}(D, \Delta)=\left\{X \in K^{d \times d} \mid X D(g)=\Delta(g) X \text { for all } g \in G\right\}
$$

contains a monomial matrix.
A proof can be found in [2]. This result will be the basis of our construction described in the next section. In fact, we will see that the irreducible representations of a supersolvable group adapted to a chief series are themselves monomial; i.e., the representing matrices of all group elements are monomial.

## 3. The algorithm

Let $\mathscr{T}=\left(G=G_{n}>G_{n-1}>\cdots>G_{0}=\{1\}\right)$ be a chief series of the supersolvable group $G$, and fix generators $g_{1}, \ldots, g_{n}$ of $G$ with $g_{i} \in G_{i} \backslash G_{i-1}$. For $1 \leq i \leq n$, define $\mathscr{T}_{i}=\left(G_{i}>G_{i-1}>\cdots>G_{0}\right)$. Let $K$ be a field containing a primitive $e$ th root of unity, where $e$ is the exponent of $G$. We will see that our construction only involves (symbolic) calculations in the group of $e$ th roots of unity; no general $K$-arithmetic is needed. To this end, we call a monomial matrix e-monomial if all of its nonzero entries are $e$ th roots of unity. A representation is called $e$-monomial if the representing matrices of all group elements are $e$-monomial. Recall that for a representation $F$ of a normal subgroup $N \triangleleft G$ and an element $g \in G$, the conjugate representation $F^{g}$ of $N$ is defined by $N \ni n \mapsto F^{g}(n):=F\left(g^{-1} n g\right)$.

Our algorithm works bottom-up along $\mathscr{T}$. At level $i, 1 \leq i \leq n$, it takes the following input:
(1) $\mathscr{F}$, a full set of nonequivalent irreducible $e$-monomial representations of $G_{i-1}$ over $K$ such that $\bigoplus_{F \in \mathscr{F}} F$ is $\mathscr{T}_{i-1}$-adapted;
(2) For every $i-1<j \leq n$, a permutation $\pi_{j}$ of $\mathscr{F}$ such that $F^{g_{j}} \sim \pi_{j} F$ for all $F \in \mathscr{F}$ as well as $e$-monomial matrices $X_{j F} \in \operatorname{Int}\left(F^{g_{j}}, \pi_{j} F\right)$, $F \in \mathscr{F}$
and computes the following output:
(1) $\mathscr{D}$, a full set of nonequivalent irreducible $e$-monomial representations of $G_{i}$ over $K$ such that $\bigoplus_{D \in \mathscr{D}} D$ is $\mathscr{T}_{i}$-adapted;
(2) For every $i<j \leq n$, a permutation $\tau_{j}$ of $\mathscr{D}$ such that $D^{g_{j}} \sim \tau_{j} D$ for all $D \in \mathscr{D}$ as well as $e$-monomial matrices $Y_{j D} \in \operatorname{Int}\left(D^{g_{j}}, \tau_{j} D\right)$, $D \in \mathscr{D}$.
Note that the input of level 1 is trivial. Level $i$ of the algorithm consists of two phases.
Phase 1. Computation of $\mathscr{D}$. Consider $F \in \mathscr{F}$ and its $g_{i}$-conjugate representation $F^{g_{i}}$.

Case 1. $\pi_{i} F=F$, i.e., $F \sim F^{g_{l}}$. Then by Clifford Theory, there are exactly $p:=p_{i}$ pairwise nonequivalent irreducible extensions $D_{0}, \ldots, D_{p-1}$ of $F$ to $G_{i}$ over $K$ satisfying $D_{k}=\chi^{k} \otimes D_{0}$, where $1=\chi^{0}, \chi^{1}, \ldots, \chi^{p-1}$ are the characters of the cyclic group $G_{i} / G_{i-1}$. If $D$ is such an extension, and $X:=D\left(g_{i}\right)$, we necessarily have
(i) $X^{-1} F(h) X=D\left(g_{i}^{-1} h g_{i}\right)=F\left(g_{i}^{-1} h g_{i}\right)=F^{g_{i}}(h)$ for all $h \in G_{i-1}$, i.e., $X \in \operatorname{Int}\left(F^{g_{i}}, F\right)$ and
(ii) $X^{p}=F\left(g_{i}^{p}\right)$.

Conversely, it is easy to see that these two conditions are also sufficient in order to define an extension of $F$ to $G_{i}$ by $D\left(g_{i}\right):=X$.

By (i), $X=c \cdot X_{i F}$ for some $c \in K^{*}$. Now we use (ii) to determine $c$ and obtain the equation

$$
c^{p} X_{i F}^{p}=F\left(g_{i}^{p}\right)
$$

This equation has $p$ distinct solutions $c_{0}, \ldots, c_{p-1}$ in $K^{*}$, which are ( $p e$ )th roots of unity. Thus $D_{0}, \ldots, D_{p-1}$ are given by

$$
D_{k}\left(g_{i}\right):=c_{k} X_{i F}
$$

As $X_{i F}$ is monomial, each $D_{k}$ is also monomial and obviously $\mathscr{T}_{i}$-adapted. Looking at the character of $D_{k}$, it is easy to see that the constants $c_{k}$ are even $e$ th roots of unity, so $D_{k}$ is $e$-monomial. Hence, this part of the construction (in particular the computation of $c_{k}$ ) only involves calculations in the group of $e$ th roots of unity.

Case 2. $\pi_{i} F \neq F$, i.e., $F \nsim F^{g_{i}}$. Again by Clifford Theory, the induced representation $F \uparrow G_{i}$ is irreducible and $\left(F \uparrow G_{i}\right) \downarrow G_{i-1}=\bigoplus_{k=0}^{p-1} F^{g_{i}^{k}}$. As $F$ is $e$-monomial, so is $F \uparrow G_{i}$. Now we have to adapt this induced representation to $\mathscr{T}_{i}$. To this end, note that $F^{g_{t}^{k}} \sim \pi_{i}^{k} F$ and $X_{i}:=X_{i \pi_{i}^{k-1} F} \cdots X_{i F} \in$ $\operatorname{Int}\left(F^{g_{i}^{k}}, \pi_{i}^{k} F\right)$. Now set $X:=\bigoplus_{k} X_{k}$ and define the representation $D$ by $D(a):=X\left(F \uparrow G_{i}\right)(a) X^{-1}$ for all $a \in G_{i}$. Obviously, $D$ is irreducible and $e$-monomial. As each $\pi_{i}^{k} F \in \mathscr{F}$ is $\mathscr{T}_{i-1}$-adapted and

$$
\left(D \downarrow G_{i-1}\right)(b)=X\left(F \uparrow G_{i} \downarrow G_{i-1}\right)(b) X^{-1}=\bigoplus_{k=0}^{p-1}\left(\pi_{i}^{k} F\right)(b)
$$

for all $b \in G_{i-1}, D$ is $\mathscr{T}_{i}$-adapted.

By these two constructions, we obtain all irreducible representations of $G_{i}$ up to isomorphism, and Phase 1 is complete.

During the construction in Phase 1, we also build a bipartite graph in which $F \in \mathscr{F}$ and $D \in \mathscr{D}$ are linked if and only if $F$ is a constituent of $D \downarrow G_{i-1}$. This "traceback" information will be be needed in the next phase.

Phase 2: Computation of $\tau_{j}$ and $Y_{j D}$. Let $F \in \mathscr{F}$ and $i<j \leq n$. We have to consider the same two cases as in Phase 1.

Case 1. $\pi_{i} F=F$. In Phase 1 , we have computed the $p$ extensions $D=$ $D_{0}, \ldots, D_{p-1}$ of $F$, where $D_{k}=\chi^{k} \otimes D$. As $D$ is an extension of $F$, we have that $\tau_{j} D$ must be an extension of $\pi_{j} F$. Let $\Delta=\Delta_{0}, \ldots, \Delta_{p-1}$ be the extensions of $\pi_{j} F$ computed in Phase 1 with $\Delta_{k}=\chi^{k} \otimes \Delta$. By Schur's lemma, $X_{j F} \in \operatorname{Int}\left(D_{k}^{g_{J}}, \tau_{j} D_{k}\right)$ for all $k$; hence we can set $Y_{j D_{k}}:=X_{j F}$, although we do not know $\tau_{j} D_{k}$ yet. To determine the $\tau_{j} D_{k}$, observe that, for $k=0$, the matrix $Y_{j D}$ satisfies

$$
Y_{j D} D^{g_{j}}\left(g_{i}\right) Y_{j D}^{-1}=\left(\tau_{j} D\right)\left(g_{i}\right)=\Delta_{l}\left(g_{i}\right)=\chi^{l}\left(g_{i} G_{i-1}\right) \cdot \Delta\left(g_{i}\right)
$$

for a unique $0 \leq l<p$. To compute $l$, we only have to look at one nonzero entry on the left side of this $e$-monomial matrix equation and the corresponding entry on the right. With this $l$, set $\tau_{j} D:=\Delta_{l}$. Once $l$ is known, the remaining values $\tau_{j} D_{k}$ can be computed by "cyclic shifts" as follows: Let $0<a_{j}<p$ be the unique integer such that $\chi^{g_{j}}=\chi^{a_{j}}$. (Note that $a_{j}$ can be directly read off the pc-presentation, see $\S 4$.) Then for $0<k<p$, we have

$$
D_{k}^{g_{j}}=\left(\chi^{k} \otimes D\right)^{g_{j}}=\left(\chi^{g_{j}}\right)^{k} \otimes D^{g_{j}} \sim \chi^{k a_{j}} \otimes \Delta_{l}
$$

Hence,

$$
\tau_{j} D_{k}=\Delta_{l+k a_{j} \bmod p}
$$

Case 2. $\quad \pi_{i} F \neq F$. In Phase 1 , we have computed a $D \in \mathscr{D}$ such that $D \downarrow G_{i-1}=\bigoplus_{0 \leq k<p} F_{k}$ with $F_{k}:=\pi_{i}^{k} F$ of degree $f$. Then $\tau_{j} D$ is the unique $\Delta \in \mathscr{D}$ such that $\Delta \downarrow G_{i-1}$ contains $\pi_{j} F$. This is already known from Phase 1. According to our construction, $\tau_{j} D \downarrow G_{i-1}=\bigoplus_{0 \leq k<p} \Phi_{k}$ with $\Phi_{k}:=\pi_{i}^{k} \Phi$ for some $\Phi \in \mathscr{F}$.

From Phase 1, we know the unique permutation $\sigma$ such that $\pi_{j} F_{k}=\Phi_{\sigma k}$ as well as $e$-monomial matrices $X_{k}:=X_{j F_{k}} \in \operatorname{Int}\left(F_{k}^{g_{j}}, \Phi_{\sigma k}\right)$.

We are looking for an $e$-monomial matrix $Y_{j D} \in \operatorname{Int}\left(D^{g_{j}}, \tau_{j} D\right)$. By Schur's lemma, $Y_{j D}$ has the form ${ }^{1}$

$$
Y_{j D}=\sigma \cdot\left(\bigoplus_{0 \leq k<p} c_{k} X_{k}\right)
$$

for suitable constants $c_{k} \in K^{*}$. To determine the $c_{k}$, note that $Y_{j D}$ must satisfy the equation

$$
\begin{equation*}
Y_{j D} D^{g_{j}}\left(g_{i}\right) Y_{j D}^{-1}=\left(\tau_{j} D\right)\left(g_{i}\right) \tag{3.1}
\end{equation*}
$$

[^1]As $Y_{j D}$ is again uniquely determined up to a constant $c \in K^{*}$, we can set $c_{0}:=1$.

According to our construction in Phase 1, there are $e$-monomial matrices $A_{k}, B_{k} \in K^{f \times f}$ such that $\left(\tau_{j} D\right)\left(g_{i}\right)$ is a block matrix of the form

$$
\left(\tau_{j} D\right)\left(g_{i}\right)=(0, \ldots, p-1) \cdot\left(B_{0} \oplus \cdots \oplus B_{p-1}\right)
$$

and $D^{g_{j}}\left(g_{i}\right)$ is a block matrix of the form

$$
D^{g_{j}}\left(g_{i}\right)=\pi \cdot\left(A_{0} \oplus \cdots \oplus A_{p-1}\right)
$$

for some $\pi \in \operatorname{Sym}(\{0, \ldots, p-1\})$. Hence, (3.1) is equivalent to
$\pi \cdot\left(\bigoplus_{k=0}^{p-1} c_{\pi k} X_{\pi k}\right)\left(\bigoplus_{k=0}^{p-1} A_{k}\right)\left(\bigoplus_{k=0}^{p-1} c_{k}^{-1} X_{k}^{-1}\right)=\sigma^{-1}(0, \ldots, p-1) \sigma \cdot\left(\bigoplus_{k=0}^{p-1} B_{\sigma k}\right)$.
Because $c_{0}=1$, we can now successively determine $c_{\pi 0}, c_{\pi^{2}} 0, \ldots$. Note that we obtain all $c_{k}$ in this way since $\pi=\sigma^{-1}(0, \ldots, p-1) \sigma$ is a $p$-cycle. To do this, it is sufficient to look at just one nonzero entry of $X_{\pi k} A_{k} c_{k}^{-1} X_{k}^{-1}$ and the corresponding entry in $B_{\sigma k}$.

## 4. Analysis

In order to analyze our algorithm, we have to describe its input and output more precisely.

The group $G$ is given as a power-commutator presentation (also called an AG-system, see [5]). This is a presentation of the form ${ }^{2}$

$$
\left\langle g_{n}, g_{n-1}, \ldots, g_{1} \mid g_{i}^{p_{i}}=u_{i}, 1 \leq i \leq n ; g_{i}^{-1} g_{j}^{-1} g_{i} g_{j}=v_{i j}, 1 \leq i<j \leq n\right\rangle
$$

with primes $p_{i}$, and words $u_{i}=g_{i-1}^{a_{i, i-1}}, \ldots, g_{1}^{a_{i}, 1}$ and $v_{i j}=g_{i}^{b_{i j, i}}, \ldots, g_{1}^{b_{i j, 1}}$. Moreover, we require that the presentation be consistent, i.e., that every word in the generators has a unique normal form $g_{n}^{e_{n}} \cdots g_{1}^{e_{1}}$ with $0 \leq e_{k}<p_{k}$. A consistent pc-presentation of this kind describes a supersolvable group. Moreover, $\left(G_{n}>G_{n-1}>\cdots>G_{1}>\{1\}\right)$, where $G_{i}:=\left\langle g_{i}, \ldots, g_{1}\right\rangle$ is a chief series of $G=G_{n}$. Conversely, every supersolvable group can be described by such a presentation.

The presentation of supersolvable groups by pc-presentations is of special interest for our purposes. A pc-presentation already contains all the information on the group needed in our algorithm, so no group operations are required at all.

With respect to this presentation, a monomial irreducible representation of the group $G_{i}$ will be given by the representing matrices of the generators $g_{i}, \ldots, g_{1}$.

As we have seen in the previous section, all nonzero entries of the monomial matrices that occur in our algorithm are $e$ th roots of unity, where $e$ is the exponent of $G$. Hence, we do not need general field arithmetic. Only symbolic computations in the group of $e$ th roots of unity are required. Representing this group as $\mathbb{Z} / e \mathbb{Z}$, this just means integer arithmetic modulo $e$. For simplicity of our analysis, we assume that $e$ is known. However, this is not necessary in

[^2]practice: Just start with $e=1$ and increase $e$ by a factor of $p$ whenever a $p$ th root cannot be computed in Case 1 of our construction.

Obviously, most of the work in our algorithm consists of multiplying, inverting, and copying $e$-monomial matrices. Choosing a suitable data structure for $e$-monomial matrices is therefore vital for our algorithm's efficiency. We represent an $n$-square monomial matrix $M$ in the form $M=\pi \operatorname{diag}\left(a_{1}, \ldots, a_{n}\right)$ by its permutation structure $\pi \in S_{n}$ and its nonzero entries $a_{1}, \ldots, a_{n}$. The permutation $\pi$ is stored as a list $\pi(1), \ldots, \pi(n)$ of integers. Under the realistic assumption that $n$ and $e$ fit into one standard one-word (e.g., 32-bit) integer on most machines, this representation uses $2 n$ words of storage.

In order to make our analysis feasible, we are only going to count the following operations: arithmetic operations in $\mathbb{Z} / e \mathbb{Z}$, multiplication and inversion of permutations, and copying of $e$-monomial matrices. Other type of operations implied by our algorithm such as evaluating permutations, table lookups, and index calculations will not be counted, but it is clear that they will not affect the order of the algorithm's running time in a reasonable implementation.

To avoid separate counting of the different kinds of operations, we express them in terms of "basic operations" as follows, roughly reflecting the relation of the actual times taken by the different kinds of opertions on a typical computer:

- each arithmetic operation in $\mathbb{Z} / e \mathbb{Z}$ is counted as 1 basic operation;
- multiplication of two permutations in $S_{n}$ or inversion of one permutation is counted as $n$ basic operations;
- copying an $n$-square $e$-monomial matrix is counted as $n$ basic operations.
Of course, these definitions are somewhat arbitrary, but they certainly match the actual running times within a constant factor. Hence again, we can be confident that our analysis determines the order of our algorithm's running time correctly.

In this model, the product of two $n$-square $e$-monomial matrices can be computed using $2 n$ basic operations according to the following formula:

$$
\pi \operatorname{diag}\left(a_{1}, \ldots, a_{n}\right) \cdot \tau \operatorname{diag}\left(b_{1}, \ldots, b_{n}\right)=\pi \tau \operatorname{diag}\left(a_{\tau(1)} b_{1}, \ldots, a_{\tau(n)} b_{n}\right)
$$

In a similar way, an $n$-square $e$-monomial matrix can be inverted in $2 n$ basic operations.

Let us now analyze level $i$ of our algorithm. In the sequel, $p:=p_{i}$ and $f$ denotes the degree of the representation $F$.

Phase 1: Computation of $\mathscr{D}$.
Case 1. $\pi_{i} F=F$.
$X_{i F}^{p}$ can be computed with at most $2 \log p \cdot 2 f=4 f \log p$ operations using square-and-multiply.
$F\left(g_{i}^{p_{i}}\right)$ : From the pc-presentation, we know that $g_{i}^{p_{i}}$ is a word of the form $g_{i-1}^{e_{i-1}} \cdots g_{1}^{e_{1}}$. Using square-and-multiply to compute matrix powers, we can hence compute $F\left(g_{i}^{p_{i}}\right)=F\left(g_{i-1}\right)^{e_{i-1}} \cdots F\left(g_{1}\right)^{e_{1}}$ with at most

$$
2 f\left(i-2+2 \sum_{k<i} \log p_{k}\right)=4 f \log \left|G_{i-1}\right|+2 f(i-2)
$$

operations.
To obtain a solution $c_{0}$ of $c^{p} X_{i F}^{p}=F\left(g_{i}^{p}\right)$, it suffices to divide a single nonzero entry of $F\left(g_{i}^{p}\right)$ by the corresponding entry of $X_{i F}^{p}$ and compute a $p$ th
root of the quotient. As computing a $p$ th root just means an integer division in our symbolic representation, this can be done with only 2 operations.

In order to obtain the $p$ extensions $D_{0}, \ldots, D_{p-1}$ of $F$ to $G_{i}$, we only have to compute the $p$ matrices $D_{k}\left(g_{i}\right)=\omega^{k} c_{0} X_{i F}$, where $\omega$ is a primitive $p$ th root of unity. This takes $2 p f$ operations.

Since $D_{k} \downarrow G_{i-1}=F$, the remaining representing matrices can be copied from level $i-1$, using $p f(i-1)$ operations.

Altogether, Case 1 takes at most

$$
4 f \log \left|G_{i}\right|+p f(i+1)+f(2 i-4)+2
$$

operations.
Case 2. $\pi_{i} F \neq F$.
As $D \downarrow G_{i-1}=\bigoplus_{0 \leq k<p} \pi_{i}^{k} F$, the matrices $D\left(g_{i-1}\right), \ldots, D\left(g_{1}\right)$ are direct sums of matrices already computed in level $i-1$ and can be obtained by copying using $p f(i-1)$ operations.

The matrix $X=\bigoplus_{k} X_{k}$, where $X_{k}=X_{i \pi_{i}^{k-1} F} \cdots X_{i F}$, can be computed in at most $2(p-2) f+f=2 p f-3 f$ operations.

It remains to compute $D\left(g_{i}\right)=X\left(F \uparrow G_{i}\right)\left(g_{i}\right) X^{-1}$. This matrix has the form

$$
\begin{aligned}
D\left(g_{i}\right) & =\left(\bigoplus_{k=0}^{p-1} X_{k}\right)(0, \ldots, p-1) \cdot\left(E_{f} \oplus \cdots \oplus E_{f} \oplus F\left(g_{i}^{p}\right)\right)\left(\bigoplus_{k=0}^{p-1} X_{k}^{-1}\right) \\
& =(0, \ldots, p-1) \cdot\left(X_{1} X_{0}^{-1} \oplus \cdots \oplus X_{p-1} X_{p-2}^{-1} \oplus X_{0} F\left(g_{i}^{p}\right) X_{p-1}^{-1}\right)
\end{aligned}
$$

As in Case 1 , computing $F\left(g_{i}^{p}\right)$ takes at most $4 f \log \left|G_{i-1}\right|+2 f(i-2)$ operations.

The inverses of $X_{1}, \ldots, X_{p-1}$ can be computed with at most $2(p-1) f$ operations. (Note that $X_{0}$ is the identity matrix.)

Finally, we have to compute $p$ products of $f$-square $e$-monomial matrices to obtain $D\left(g_{i}\right)$ according to the above formula. This takes at most $2 p f$ operations.

Altogether, Case 2 takes at most $4 f \log \left|G_{i-1}\right|+p f(i+5)+f(2 i-9)$ operations for the $p f$-dimensional representations $\pi_{i}^{k} F$ of $G_{i-1}$, that is,

$$
\frac{4}{p} f \log \left|G_{i-1}\right|+f(i+5)+\frac{f}{p}(2 i-9)
$$

operations each.
Phase 2: Computation of $\tau_{j}$ and $Y_{j D}$. Let $F \in \mathscr{F}$ and $i<j \leq n$.
Case 1. $\pi_{i} F=F$. For each $i<j \leq n$, we have to do the following:
The matrices $Y_{j D_{k}}=X_{j F} \quad(0 \leq k<p)$ are copies from level $i-1$ in $p f$ operations.

To compute $l$, we have to compute one nonzero entry of $Y_{j D} D^{g_{j}}\left(g_{i}\right) Y_{j D}^{-1}$ and divide it by the corresponding entry of $\Delta\left(g_{i}\right)$.

First, we compute $D^{g_{j}}\left(g_{i}\right)=D\left(g_{j}^{-1} g_{i} g_{j}\right)$ : From the pc-presentation, we know that $g_{j}^{-1} g_{i} g_{j}$ is a word of the form $g_{i}^{e_{i}} \cdots g_{1}^{e_{1}}$. Hence, $D^{g_{j}}\left(g_{i}\right)$ can be computed in at most $4 f \log \left|G_{i}\right|+2 f(i-1)$ operations (see Case 1 of Phase 1).

Next, we compute one nonzero entry of $Y_{j D} D^{g_{j}}\left(g_{i}\right) Y_{j D}^{-1}$ with 3 more operations.

To obtain $l$, we divide this entry by the corresponding entry of $\Delta\left(g_{i}\right)$ and compute the $p$ th root of the quotient, which is a $p$ th root of unity. As this just means an integer division in our symbolic representation, it takes 2 more operations to compute $l$.

Now the $\tau_{j} D_{k}$ can be obtained by "cyclic shifts", which are free of cost in our model.

Altogether, Case 1 takes at most

$$
4 f \log \left|G_{i}\right|+p f+f(2 i-2)+5
$$

operations.
Case 2. $\pi_{i} F \neq F$. For each $i<j \leq n$, we have to do the following: $\tau_{j} D$ can be determined free of cost by table lookups.
Next we determine the coefficients $c_{k}, 0<k<p$. For each coefficient, we have to compute one nonzero entry of $X_{\pi k} A_{k} c_{k}^{-1} X_{k}^{-1}$ and divide it by the corresponding entry of $B_{\sigma k}$. Altogether, this takes $5 p-5$ operations.

Finally, in order to obtain $Y_{j D}$, we have to compute $c_{2} X_{2}, \ldots, c_{p-1} X_{p-1}$. This takes at most $2(p-1) f$ operations.

Altogether, Case 2 takes at most $2 p f-2 f+5 p-5$ operations for $p f$ dimensional representations of $G_{i-1}$, that is,

$$
2 f-2 \frac{f}{p}+5-f \frac{5}{p}
$$

operations each.
Altogether, we have proved the following.
Lemma 4.1. The number of operations taken to process one $f$-dimensional representation of $G_{i-1}$ in both phases is at most

$$
8 f \log \left|G_{i}\right|+p f(i+2)+f(4 i-6)+7
$$

for Case 1, and at most

$$
\frac{4}{p} f \log \left|G_{i-1}\right|+f(i+7)+\frac{f}{p}(2 i-11)+5-\frac{5}{p}
$$

for Case 2.
As the first case is obviously more expensive than the second, our worst-case analysis will be based on Case 1. If we sum up over all representations $F \in \mathscr{F}$ and use the fact that $\sum_{F \in \mathscr{F}} \operatorname{deg} F \leq\left|G_{i-1}\right|$, we obtain the upper bound

$$
\begin{aligned}
& 8\left|G_{i-1}\right| \log \left|G_{i}\right|+\left|G_{i}\right|(i+2)+\left|G_{i-1}\right|(4 i+1) \\
& \quad \leq 4\left|G_{i}\right| \log \left|G_{i}\right|+\left|G_{i}\right|(i+2)+\left|G_{i}\right|(2 i+1 / 2) \\
& \quad \leq 4\left|G_{i}\right| \log \left|G_{i}\right|+3\left|G_{i}\right| i+2.5\left|G_{i}\right| \\
& \quad \leq 7\left|G_{i}\right| \log \left|G_{i}\right|+2.5\left|G_{i}\right|
\end{aligned}
$$

for the number of operations in level $i$ of the algorithm.

Summing up over all levels $1 \leq i \leq n$, we obtain the upper bound

$$
\begin{aligned}
& 7 \sum_{i=1}^{n} \quad\left|G_{i}\right| \log \left|G_{i}\right|+2.5 \sum_{i=1}^{n}\left|G_{i}\right| \\
& \quad \leq 7 \log \left|G_{n}\right| \sum_{i=1}^{n}\left|G_{i}\right|+2.5 \sum_{i=1}^{n}\left|G_{i}\right| \\
& \quad \leq 7 \log \left|G_{n}\right| \sum_{i=1}^{n}\left|G_{n}\right| 2^{i-n}+2.5 \sum_{i=1}^{n}\left|G_{n}\right| 2^{i-n} \\
& \quad \leq 7\left|G_{n}\right| \log \left|G_{n}\right| \sum_{i=0}^{n-1} 2^{-i}+2.5\left|G_{n}\right| \sum_{i=0}^{n-1} 2^{-i} \\
& \quad<14\left|G_{n}\right| \log \left|G_{n}\right|+5\left|G_{n}\right|
\end{aligned}
$$

for the total number of operations of our algorithm, and we have proved the following.

Theorem 4.1. The ordinary irreducible representations of a supersolvable group $G$ can be computed from a power-commutator presentation of $G$ with at most

$$
14|G| \log |G|+5|G|=O(|G| \log |G|)
$$

basic operations.
Observe that the output of our algorithm consists of $2 n \sum_{D \in \mathscr{D}} \operatorname{deg} D$ integer numbers, where $\mathscr{D}$ denotes the set of irreducible representations of $G$ computed in level $n$. Obviously, this is at most $2|G| \log |G|$. On the other hand, this upper bound is sharp for abelian 2-groups. Although it does not prove a lower complexity bound, this indicates that our algorithm is (in terms of the group order) optimal up to a constant factor.

We have not yet implemented our algorithm. However, it can be expected to run substantially faster than the old algorithm, for which some running times are given in [2].

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Institut für Informatik, Universität Bonn, Römerstr. 164, 53117 Bonn, Germany
E-mail address: uli@leon.cs.uni-bonn.de
E-mail address: clausen@leon.cs.uni-bonn.de


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[^1]:    ${ }^{1}$ For notational convenience, we are going to identify a permutation $\sigma \in \operatorname{Sym}(\{0, \ldots, p-1\})$ with the $p f$-square block permutation matrix $P_{\sigma} \otimes E_{f}$, where $P_{\sigma}$ is the $p$-square permutation matrix corresponding to $\sigma$ and $E_{f}$ denotes the $f$-square identity matrix.

[^2]:    ${ }^{2}$ Originally, pc-presentations have been defined to present solvable groups. We use a slightly modified form suited to the class of supersolvable groups.

